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A New Distributed Algorithm for Finding Dominating Sets in IoT Networks under Multiple Criterias

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1 Introduction

The various tasks of everyday life have never been easier thanks to wireless sensor networks that are continually expanding in many areas, like forest fire detection [4], harvesting [8], intrusion detection [2], [10], etc. These networks are composed of a set of microsensors called nodes, which can collect and transmit data autonomously. These microsensors are often deployed randomly in a region of interest. This randomness makes it difficult to determine the topology of the network.

Energy and efficiency are the most recurrent problems in wireless sensor networks. Since energy is a resource, often non-renewable and limited, it is of great interest to preserve it and to optimize its use. The effectiveness of a wireless sensor network, and its ability to perform the task assigned to it, is part of the quality of service of this network. These two objectives are mutually contradictory and require a compromise to ensure a quality network that can serve for a long duration by minimizing the energy.

The authors of [1] propose a centralized algorithm for the construction of a connected dominating set based on multipoint relays. The authors of [7] propose a new distributed greedy algorithm for approximating the construction of a minimal connected dominating set. The authors claim that their method obtains good results in terms of construction cost compared to classical algorithms. The authors of [5] propose a system of clustering, called EBDSC, based on dominating sets that effectively extend the lifetime of the network by balancing the energy consumption between different nodes.

The main idea of this work is to detect a connected dominating set, which will be designated to perform special tasks and serve other nodes of the network. This strategy aims to reduce communication overhead and increase bandwidth efficiency, reduce overall energy consumption, and ultimately to extend the effective lifetime of the network. For this purpose, we introduce a new distributed algorithm for the search of the nodes forming connected dominating set in a wireless sensor network, using a new concept called wait before start, which allows each dominating node to declare itself the number of its neighbors and its residual energy. This method is based on a delayed start of each sensor with respect to an associated value. If the value refers to the number of neighbors, then the sensor having the maximum number of neighbors so far, will start the process first, so that its waiting time for an associated value corresponds to the energy consumed up to the instant $t$, and so on for all the nodes of the
network. This procedure is hybridized with the iterative local aggregation method proposed by [9]. The results of the simulation on several randomly generated networks show that the proposed method guarantees the generation of a dominating set using two criteria: the number of neighbors and the remaining energy.

2 Problem formulation

The dominating set problem in a graph representing a wireless sensor network consists in finding the minimum number of nodes that communicate with all the other nodes of the network. For example, the set of red nodes in the Figures 1(b) or (c) represents a dominating set of minimum size because it is not possible to find a set with less than two nodes which are connected to all other nodes. However, the set of red nodes in Figure 1(a) is a dominating set but not of minimum size.

![FIG. 1: Dominating sets.](image)

2.1 Definition of criteria (attributes)

The two criteria defined in this work are:

**Maximizing the total degree of the dominating set ($z_1$):** This criterion is very important to optimize the realization of the various tasks assigned to the network. In the proposed algorithm we interpret this criterion by choosing vertices of greater degrees.

**Maximizing network lifetime ($z_2$):** The lifetime of a network is ensured by the batteries of the sensors. Optimizing this objective means to avoid the use of sensors whose battery level is too low.

Note that these two criteria are contradictory, because a user tends to use the same nodes (those covering the greatest number of other nodes). But this implies an energy consumption that is not uniform. Thus the lifetime of the network will not be optimal.

2.2 Definition of actions (alternatives)

In this work, we have to carry out the selection of a dominating set in a periodical way to ensure the two criteria defined previously. Consequently, the set actions is defined by the nodes of a network.

3 The iterative local aggregation method

This method is introduced by [9], it can be summarized as follows:

**a research phase:** exploitation of information to integrate the preferences of the decision-maker,

**a reset phase:** elaboration of a new proposal to be submitted to the decision-maker,
a phase of reaction: during this phase the decision-maker is directly involved in the decision-making process and issues an opinion on the latest proposal. His opinion is taken care of by the analyst.

The satisfaction of the decision-maker is seen as a condition for stopping this process. In the IoT networks, in the beginning, the residual energy is the same in each node. Therefore the second criterion does not have a significant influence on the selection. It is after a period (often defined statistically) noted $\tau$ that the energy factor will have its importance. We then proposed the hanging:

weight of the attribute $z_1$: $w_1 = E(d_{max})$,

weight of the attribute $z_2$: $w_2 = y_1(1 - E(d_{max}))$,

where:

$E(d_{max})$ is the residual energy of the node having the maximum degree in the network, and $y_1 = 1$ if $t > \tau$ and equal to 0 otherwise.

4 Functions and message primitives

The distributed algorithms presented in this work use some primitive functions that we describe in Table 1.

TAB. 1: Functions of the proposed algorithms.

<table>
<thead>
<tr>
<th>Function</th>
<th>Definition</th>
<th>Function</th>
<th>Definition</th>
</tr>
</thead>
<tbody>
<tr>
<td>send(m,*)</td>
<td>sends the message m in a broadcast</td>
<td>rand(a,b)</td>
<td>generates an integer random value between a and b exclusive</td>
</tr>
<tr>
<td>read()</td>
<td>waits for receipt of messages. This function is blocking. If there is no received message any more, it remains blocked in this instruction</td>
<td>read(wt)</td>
<td>waits for receipt of messages. If there is no received message after $wt$ milliseconds then the execution will continue and go to the next instruction</td>
</tr>
<tr>
<td>getTime()</td>
<td>returns the local time of a node</td>
<td>getId()</td>
<td>returns the node identifier</td>
</tr>
<tr>
<td>getNNeig()</td>
<td>returns the number of neighbors of the node</td>
<td>stop()</td>
<td>stops the execution of the program</td>
</tr>
</tbody>
</table>

5 The WBS algorithm

This problem is an NP-Hard problem [3], which means that no algorithm can solve it in polynomial time. In this work, we will use a classical heuristic described by Algorithm 1. To illustrate the operation of this algorithm, we first consider a network with a set of nodes $V$. The algorithm selects a node of maximum degrees and adds it to the set $D$ (the current dominating set). Then, the selected node and its neighbors are eliminated from $V$. This procedure is repeated on the resulting graph as many times as necessary until $V$ is empty. The set $D$ obtained this way clearly represents a dominating set of the network.
We use a new concept called WBS (Wait-Before-Starting), in which the start time of each node depends on its value. The value chosen for this work is the number of neighbor of each node weighted with its residual energy. The weighting is carried out by an iterative local aggregation method, i.e., in the life cycle of an IoT network, the energy criterion brings little, since the majority of the batteries of the sensors are full. The process used in this work gives an increasing weight to the energy criterion, as our network works and loses energy. The pseudo-code of the WBS concept is given by Algorithm 2.

**Algorithm 1:** The pseudo-code of the centralized heuristic of finding the dominating set

```plaintext
Data: V
Result: D
D = ∅;
while (S ≠ ∅) do
    n = argmax(\(N(s)\));  e = argmax(\(N(s)\));
    D = D ∪ \{n\};  V = V − N(n);  V = V − \{n\};
end
```

6 Proposed distributed version and results

In this section, we will present the multicriteria and a distributed version of the heuristic presented in the previous section. It works as follows: each node performs the weighting explained in Section 3, and then we use the WBS concept to start the algorithm with the sensor node having the maximum weighted value. It will be admitted as a dominating node. Then, it deactivates its neighbors by sending a message T1, this step corresponds to lines 4, 5 and 6 of the Algorithm 1, then it deactivates itself. This process is repeated until \(V = ∅\). This procedure is reproduced from the weighting periodically to find all compromise solutions. Algorithm 3 shows the pseudo-code of this process which represents the distributed version of the heuristic presented by Algorithm 1.

**Algorithm 2:** WBS: The pseudo-code of the WBS algorithm

```plaintext
Data: x, gt
Result: D
once = false;  t = x × gt;
while (true) do
    r_x = read(t);
    if (r_x==null) then
        send(A, *); stop();
    end
    if (r_x==A and once==false) then
        once = true; send(A, *); stop();
    end
end
```

**Algorithm 3:** The pseudo-code of the distributed version of the heuristic presented by Algorithm 1.
Data: $G = (V, E)$

Result: $D$

id = getId(); n = getNNeig(); b = rand(1, 100); once1 = false; once2 = false;
w = (50−n)*100+b; ts = getTime(); te = ts+w; dominating = false;

while (true) do
  loop wait w; t = getTime(); read message;
  if (message==null) then
    dominating = true; send(T1); stop();
  else
    if ((message==T1) and (once1==false)) then
      once1 = true; send(T2); stop();
    end
  end
  if ((message==T2) and (once2==false)) then
    once2 = true; n = n−1; b = rand(1, 100);
    nw = (50−n)*100+b; w = ((nw−w)+(te−t));
  end
end

Algorithm 3: The pseudo-code of the distributed heuristic for finding the dominating set

For the implementation of this algorithm, we used the CupCarbon [6] simulator. Figure 2 shows an example of a dominating set (yellow nodes) obtained by the proposed method.

FIG. 2: An example showing 23 nodes dominating a total of 200 nodes.

7 Conclusion

In this work, we have presented a new distributed algorithm for the dominating set problem in an IoT network under several screens. This algorithm uses the Wait-Before-Starting (WBS) concept to independently determine the dominating nodes and the iterative local weighting method. In this concept, each value is time-weighted, each node in the network will begin executing its program after a specified time associated with its value. In this work, this value represents the number of neighbors of a node and its residual energy.

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References


